

PIC Microcontroller and Embedded Systems

Branch, Call and Delay Loop

1

OUTLINE

- ▶ Looping in PIC
- ▶ Loop inside loop
- ▶ Other conditional jumps
- ▶ All conditional branches are short jumps
- ▶
- ▶ Unconditional branch instruction

2

Looping in PIC

- ▶ Repeat a sequence of instructions or a certain number of times
- ▶ Two ways to do looping
 - Using DECFSZ instruction
 - Using BNZ\BZ instructions

3

DECFSZ instruction

Decrement file register, skip the next instruction if the result is equal 0

- DECFSZ fileRef, d
- GOTO instruction follows DECFSZ
- Write a program to a) Clear WREG
- b) Add 3 to WREG ten times and place the result in SFR PORTB

```

COUNT EQU 0x25
        MOVLW d'10'
        MOVWF COUNT
        MOVLW 0
AGAIN   ADDLW 3
        DECFSZ COUNT,F
        GOTO AGAIN
        MOVWF PORTB

```

4

Using BNZ\BZ instructions

- ▶ Supported by PIC18 families
 - Early families such as PIC16 and PIC12 doesn't support these instruction
- ▶ These instructions check the status flag

Back

```
DECF fileReg, f
BNZBack
```

5

Example

Write a program to

- a) Clear WREG
- b) Add 3 to WREG ten times and place the result in SFR PORTB

- Solution

```

COUNT EQU 0x25
MOVLW d'10'
MOVWF COUNT
MOVLW 0
AGAIN ADDLW 3
      DECF COUNT, F
      BNZ AGAIN
      MOVWF PORTB
```

6

Loop inside a loop

Write a program to

- Load the PORTB SFR register with the value 55H
- Complement PORTB **700**times

Solution

```

R1 EQU0x25
R2 EQU0x26
COUNT_1 EQUd'10'
COUNT_2 EQUd'70'
MOVLW0x55
MOVWFPORTRB
MOVLWCOUNT_1
LOP_1    MOVWFR1
         MOVLWCOUNT_2
         MOVWFR2
LOP_2    COMPPORTRB,F
         DECFR2,F
         BNZLOP_2
         DECFR1,F
         BNZLOP_1

```

7

Other conditional jumps

- All of the 10 conditional jumps are 2-byte instructions
- They requires the target address
 - 1 byte address (short branch address)
 - Relative address
- Recall: MOVF will affect the status Reg.
- In the BZ instruction, the Z flag is checked. If it is high, that is equal 1, it jumps to the target address

8

Flag Bits and Decision Making

BC	k	Branch relative if Carry
BNC	k	Branch relative if Not Carry
BN	k	Branch relative if Negative
BNN	k	Branch relative if Not Negative
BOV	k	Branch relative if Overflow
BNOV	k	Branch relative if Not Overflow
BZ	k	Branch relative if Zero
BNZ	k	Branch relative if Not Zero

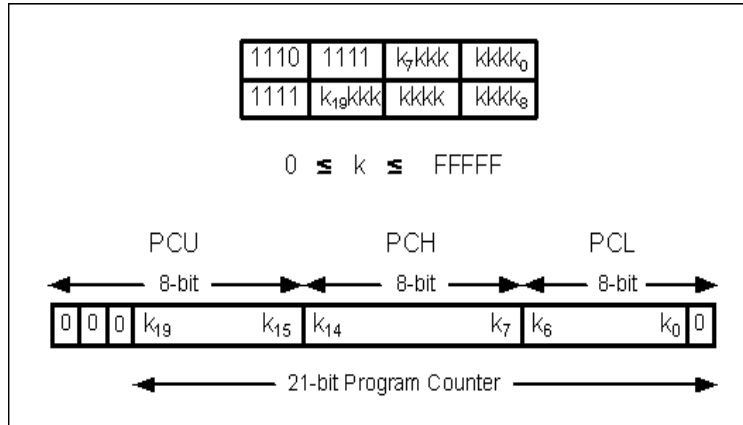
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Unconditional branch instruction

- ▶ Control is transferred unconditionally to the target location (at ROM)
- ▶ Two unconditional branches
 - GOTO
 - BRA

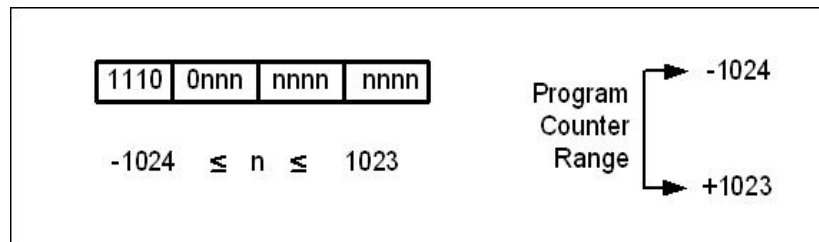
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GOTO Instruction



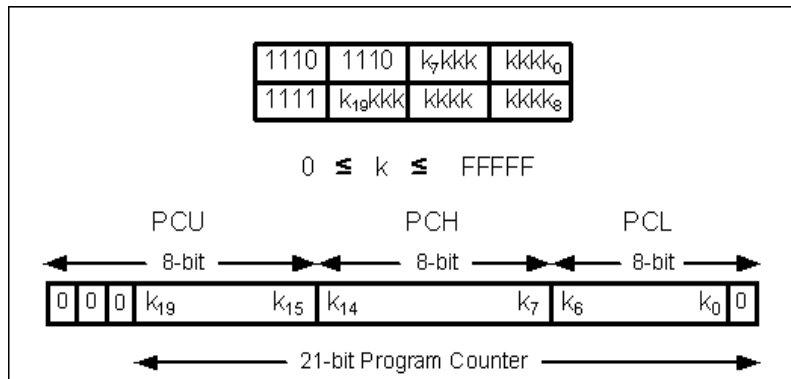
11

BRA Instruction



12

Call instruction



13

CALL Instruction

- Control is transferred to subroutine
- Current PC value, the instruction address just below the CALL instruction, is stored in the stack
 - push onto the stack
- Return instruction is used to transfer the control back to the caller,
 - the previous PC is popped from the stack

14

Stack and Stack Pointer (SP)

- Read/Write Memory
- Store the PC Address
 - 21-bit (000000 to 1FFFFFF)
- 5-bit stack, total of 32 locations
- SP points to the last used location of the stack
 - Location 0 doesn't used
 - Incremented pointer

15

RCALL (Relative Call)

- ▶ 2-Byte instruction
- ▶ The target address must be within 2K
 - 11 bits of the 2 Byte is used
- ▶ Save a number of bytes.

16

Delay Calculating for PIC18

- Two factors can affect the accuracy of the delay
 1. The duration of the clock period, which is function of the Crystal freq Connected to OSC! And OSC2
 2. The instruction cycle duration
 - Most of the PIC18 instructions consumes 1 cycle
 - Use Harvard Architecture
 - Use RISC Architecture
 - Use the pipeline concept between fetch and execute

17

Instruction Cycle time for the PIC

- What is the Instruction Cycle ?
- Most instructions take one or tow cycles
 - BTFSS can take up to 3 cycles
- Instruction Cycle depends on the freq. of oscillator
- Clock source: Crystal oscillator and on-chip circuitry
- One instruction cycle consists of four oscillator period

18

Example

- ▶ Find the period of the instruction cycle you chose 4 MHz crystal? And what is required time for fetching an instruction?

- ▶ Solution

$$4 \text{ MHz}/4 = 1 \text{ MHz}$$

$$\text{Instruction Cycle} = 1/1\text{MHz} = 1 \text{ usec}$$

$$\text{Fetch cycle} = 4 * 1 \text{ usec} = 4 \text{ usec}$$

19

Example

Find how long it take to execute each of the following instructions for a PIC18 with 4 MHz

- MOVLW
- ADDLW
- CALL
- DECF
- GOTO
- NOP
- BNZ
- MOVWF

20

Delay calculation for PIC18 Example

- Find the size of the delay in the following program if the crystal freq. is 4MHz.

```

DELAY    MOVLW 0xFF
          MOVWF MYREG
AGAIN    NOP
          NOP
          DECF MYREG, F
          BNZ AGAIN
          RETURN
  
```

21

Example

```

          MYREG EQU 0x08
          ORG 0
BACK     MOVLW 0x55
          MOVWF PORTB
          CALL DELAY
          MOVLW 0xAA
          MOVWF PORTB
          CALL DELAY
          GOTO BACK

          ORG 300H
DELAY    MOVLW 0xFA
          MOVWF MYREG
AGAIN    NOP
          NOP
          NOP
          DECF MYREG, F
          BNZ AGAIN
          RETURN
  
```

22

Example

```

R2    EQU0x2
R3    EQU0x3
R4    EQU0x4
MOVLW    0x55
MOVWF    PORTB
BACK
CALL
DELAY_500MS
COMF    PORTB
GOTO    BACK

```

```

DELAY_500MS
    MOVLW    D'20'
    MOVWF    R4
BACK
    MOVLW    D'100'
    MOVWF    R3
AGAIN
    MOVLW    D'250'
    MOVWF    R2
HERE
    NOP
    NOP
    DECF    R2, F
    BNZ    HERE
    DECF    R3, F
    BNZ    AGAIN
    DECF    R4, F
    BNZ    BACK
    RETURN

```